

**DW OR PW PACKAGE**

## **3.3-V, 12-BIT, 30 MSPS, LOW-POWER ANALOG-TO-DIGITAL CONVERTER WITH POWER DOWN**

## **FEATURES**



- •**Copiers**
- •**Communications**
- •**Test Instruments**
- •**IF and Baseband Digitization**

## **DESCRIPTION**

The THS1230 is <sup>a</sup> CMOS, low-power, 12-bit, 30 MSPS analog-to-digital converter (ADC) that operates with <sup>a</sup> 3.3-V supply. The THS1230 gives circuit developers complete flexibility. The analog input to the THS1230 is differential with <sup>a</sup> gain of 0.5 for Mode 2 and 1.0 for Mode 1. The THS1230 provides <sup>a</sup> wide selection of voltage references to match the user's design requirements. For more design flexibility, the internal reference can be bypassed to use an external reference to suit the dc accuracy and temperature drift requirements of the application. The out-of-range output is used to monitor any out-of-range condition in the THS1230's input range.

The speed, resolution, and single-supply operation of the THS1230 are suited for applications in set top box (STB), video, multimedia, high-speed acquisition, and communications. The speed and resolution ideally suit charge-couple device (CCD) input systems such as digital copiers, digital cameras, and camcorders. The wide input voltage range between  $V_{REFB}$  and  $V_{REFT}$  allows the THS1230 to be designed into multiple systems.

The THS1230C is characterized for operation from 0°C to 70°C. The THS1230I is characterized for operation from –40°C to 85°C.



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This integrated circuit can be damaged by ESD. Texas Instruments recommends that all integrated circuits be handled with appropriate precautions. Failure to observe proper handling and installation procedures can cause damage.

ESD damage can range from subtle performance degradation to complete device failure. Precision integrated circuits may be more susceptible to damage because very small parametric changes could cause the device not to meet its published specifications.



#### **ORDERING INFORMATION**

(1) For the most current specifictions and package information refer to our Web site at www.ti.com.

## **FUNCTIONAL BLOCK DIAGRAM**



## **TERMINAL FUNCTIONS**



## **ABSOLUTE MAXIMUM RATINGS(1)**

over operating free-air temperature range (unless otherwise noted)



(1) Stresses beyond those listed under "absolute maximum ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated under "recommended operating conditions" is not implied. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.



## **RECOMMENDED OPERATING CONDITIONS**

over operating free-air temperature range,  $T_A$  (unless otherwise noted)



(1) Based on  $V_{REF} - V_{REFB} = 1.0 V$ , varies proportional to the  $V_{REF} - V_{REFB}$  value. AIN+ and AIN– inputs must always be greater than 0 V and less than AV<sub>DD</sub>.

(2)  $\,$  Clock pin is referenced to AGND and powered by AV<sub>DD</sub>.

(3) Clock frequency can be extended to this range without degradation of performance.

## **ELECTRICAL CHARACTERISTICS**

over recommended operating conditions (AV<sub>DD</sub> = DV<sub>DD</sub> = 3.3 V,  $f_s$  = 30 MHz/50% duty cycle, MODE = 1, 1-V input span, internal reference, T<sub>min</sub> to T<sub>max</sub>) (unless otherwise noted)



Time for ADC conversions to be accurate to within  $\widetilde{0.1\%}$  of fullscale, INT ckts.

(1) Time for reference to recover to 1% of its final voltage level.<br>
(2) Time for ADC conversions to be accurate to within 0.1% of  $(3)$  Clock = 30 MHz, AIN+ and AIN- at Common Mode or 1.65  $Clock = 30 MHz$ , AIN+ and AIN– at Common Mode or 1.65 V DC.

 $(4)$  Clock = 30 MHz, fin = 3.58 MHz at -1 dBFS.



## **ELECTRICAL CHARACTERISTICS (CONTINUED)**

over recommended operating conditions (AV<sub>DD</sub> = DV<sub>DD</sub> = 3.3 V,  $f_s$  = 30 MHz/50% duty cycle, MODE = 1, 1-V input span, internal reference, T<sub>min</sub> to T<sub>max</sub>) (unless otherwise noted)



(1) The internal reference voltage is not intended for use driving off chip.



**Figure 1. Reference Generation**

## **ELECTRICAL CHARACTERISTICS (CONTINUED)**

over recommended operating conditions (AV<sub>DD</sub> = DV<sub>DD</sub> = 3.3 V,  $f_s$  = 30 MHz/50% duty cycle, MODE = 1, 1-V input span, internal reference, T<sub>min</sub> to T<sub>max</sub>) (unless otherwise noted)



(1) Input amplitudes for all single tone dynamic tests are at –1 dBFS, all supplies <sup>=</sup> 3.3 V.

(2) The clock frequency may be extended to 5 MHz without degradation in specified performance.

#### **PARAMETER MEASUREMENT INFORMATION**



**Figure 3. Output Enable Timing**

#### **TYPICAL CHARACTERISTICS**





## **TYPICAL CHARACTERISTICS (continued)**



## **TYPICAL CHARACTERISTICS (continued)**



## **PRINCIPLES OF OPERATION**

## **Analog Input**

The analog input AIN is sampled in the sample and hold unit, the output of which feeds the ADC CORE, where the process of analog to digital conversion is performed against ADC reference voltages,  $V_{REF}$  and  $V_{REF}$ .

Connecting the EXTREF pin to one of two voltages, DGND or  $DV_{DD}$  selects one of the two configurations of ADC reference generation. The ADC reference voltages come from either the internal reference buffer or completely external sources. Connect EXTREF to DGND for internal reference generation or to  $DV_{DD}$  for external reference generation.

CON0 and CON1 as described below, select the input configuration mode or place the device in powerdown. The ADC core drives out through output buffers to the data pins D0 to D11. The output buffers can be disabled by the  $\overline{OE}$  pin.

A single, sample-rate clock (30 MHz maximum) is required at pin CLK. The analog input signal is sampled on the rising edge of CLK, and corresponding data is output after the fifth following rising edge.

The THS1230 can operate in differential Mode 1 or differential Mode 2, controlled by the configuration pins CON0 and CON1 as shown in Table 1. Mode 0 places the device in power-down state or standby for reduced power consumption.



<b>MODE</b>	CON <sub>1</sub>	<b>CON0</b>	<b>MODE OF OPERATION</b>	
		0	Device powered down	
			Differential mode $\times$ 1	
		0	Differential mode $\times$ 0.5	
			Not used	

**Table 1. Input Modes of Operation**

Modes 1 and 2 are shown in Figure 14.



**Figure 14. Input Mode Configurations**

The gain of the sample and hold changes with the CON1 and the CON0 inputs. Table 2 shows the gain of the sample and hold and the levels applied at the AIN+ and AIN- analog inputs for Mode 1 and Mode 2. The common mode level for the two analog inputs is at AVDD/2.

<b>MODE</b>	CON <sub>1</sub>	<b>CON0</b>	$(AIN+) - (AIN-)$ <b>MIN</b>	$(AIN+) - (AIN-)$ <b>MAX</b>	<b>S/H GAIN</b>
			$-1$ V		×1
			$-2V$	2 V	$\times 0.5$

**Table 2. Input Mode Switching**

Table 2 assumes that the delta in ADC reference voltages  $V_{REFT}$  and  $V_{REFB}$  is set to 1 V, i.e.,  $V_{REFT} - V_{REFB} = 1$ V. Note that  $V_{REFB}$  and  $V_{REFT}$  can be set externally, which will scale the numbers given in this table.

The user-chosen operating configuration and reference voltages determine what input signal voltage range the THS1230 can handle.

The following sections explain both the internal signal flow of the device and how the input signal span is related to the ADC reference voltages, as well as the ways in which the ADC reference voltages can be buffered internally or externally applied.

## **Signal Processing Chain (Sample and Hold, ADC)**

[Figure](#page-12-0) 15 shows the signal flow through the sample and hold unit and the PGA to the ADC core.

<span id="page-12-0"></span>

**Figure 15. Analog Input Signal Flow**

## **Sample and Hold**

The differential sample and hold processes  $A_{IN}$  with respect to the voltages applied to the REFT and REFB pins, to give a differential output  $(VP+) - (VP-) = VP$  given by:

• $VP = (AIN+) - (AIN-)$ 

## **Analog-to-Digital Converter**

No matter what operating configuration is chosen, VP is digitized against ADC reference voltages  $V_{REFT}$  and VREFB. The VREFT and VREFB voltages set the analog input span limits FS+ and FS-, respectively. Any voltages at AIN greater than REFT or less than REFB causes ADC over-range, which is signaled by OVR going high when the conversion result is output.

## **Analog Input**

A first-order approximation for the equivalent analog input circuit of the THS1230 is shown in Figure 16. The equivalent input capacitance C<sub>I</sub> is 5 pF typical. The input must charge/discharge this capacitance within the sample period of one half of <sup>a</sup> clock cycle. When <sup>a</sup> full-scale voltage step is applied, the input source provides the charging current through the switch resistance R<sub>SW</sub> (200 Ω) of S1 and quickly settles. In this case the input impedance is low. Alternatively, when the source voltage equals the value previously stored on  $C<sub>1</sub>$ , the hold capacitor requires no input current and the equivalent input impedance is very high.



**Figure 16. Simplified Equivalent Input Circuit**

To maintain the frequency performance outlined in the specifications, the total source impedance should be limited to the following equation with f<sub>CLK</sub> = 30 MHz, C<sub>I</sub> = 5 pF, R<sub>SW</sub> = 200 Ω:

$$
R_{\mathsf{S}} < \frac{1}{2\mathsf{f}_{\mathsf{CLK}} \times C_{\mathsf{I}} \times \ln(256)} - R_{\mathsf{SW}}
$$

So, for applications running at a lower  $f_{CLK}$ , the total source resistance can increase proportionally.



The analog input of the THS1230 is <sup>a</sup> differential input that can be configured in various ways depending on the signal source and the required level of performance. A fully differential connection (see Figure 17) delivers the best performance from the converter.



**Figure 17. AC-Coupled Differential Input**

The analog input can be dc-coupled (see [Figure](#page-14-0) 18) as long as the inputs are within the analog input common mode voltage range. For example (see [Figure](#page-14-0) 18), V+ and V– are signals centered on GND with <sup>a</sup> peak-to-peak voltage of 2 V, and the circuit in [Figure](#page-14-0) 18 is used to interface it with the THS1230. Assume  $AV_{DD}$  of the converter is 3 V. Two problems have to be solved. The first is to shift common mode level (CML) from 0 V to 1.5 V ( $AV<sub>DD</sub>/2$ ). To do that, a V bias voltage and an adequate ratio of R1 and R2 have to be selected. For instance, if V bias =  $AV_{DD}$  = 3 V, then R1 = R2. The second is that the differential voltage has to be reduced from 4 V (2 x 2 V) to 1 V, and for that an attenuation of 4 to1 is needed. The attenuation is determined by the relation:  $(R3||2R2)/((R3||2R2) + 2R1)$ . One possible solution is R1 = R2 = R3 = 150  $\Omega$ . In this case, moreover, the input impedance (2R1 + (R3||2R2)) will be 400  $\Omega$ . The values can be changed to match any other input impedance. A capacitor, C, connected from AIN+ to AIN– helps filter any high frequency noise on the inputs, also improving performance. Note that the chosen value of capacitor C must take into account the highest frequency component of the analog input signal.

<span id="page-14-0"></span>

**Figure 18. DC-Coupled Differential Input Circuit**

A single-ended source may give better overall system performance when it is converted to <sup>a</sup> differential signal before driving the THS1230. The configuration in Figure 19 takes <sup>a</sup> VIN of 1 V and drives the 1:1 transformer ratio so that value of AIN+ and AIN– converts to fullscale value at the ADC digital output. With VIN at –1 V the value at AIN+ and AIN– converts to 0 at the ADC digital outputs.



**Figure 19. Transformer Coupled Single-Ended Input**

## **Digital Outputs**

The output of THS1230 is in unsigned binary code. The ADC input over-range indicator is output on pin OVRNG. Capacitive loading on the output should be kept as low as possible (a maximum loading of 10 pF is recommended) to ensure best performance. Higher output loading causes higher dynamic output currents and can therefore increase noise coupling into the part's analog front end. To drive higher loads the use of an output buffer is recommended.



When clocking output data from THS1230, it is important to observe its timing relation to CLK. The pipeline ADC delay is 5 clock cycles to which the maximum output propagation delay needs to be added.



**Figure 20. Buffered Output Connection**





## **Layout, Decoupling and Grounding Rules**

Proper grounding and layout of the PCB on which THS1230 is populated is essential to achieve the stated performance. It is advised to use separate analog and digital ground planes that are spliced underneath the IC. THS1230 has digital and analog pins on opposite sides of the package to make this easier. Because there is no connection internally between analog and digital grounds, they have to be joined on the PCB. It is advised to do this at one point in close proximity to THS1230.

Because of the high sampling rate and switched-capacitor architecture, THS1230 generates transients on the supply and reference lines. Proper decoupling of these lines is therefore essential. Decoupling is recommended as shown in the schematic of the THS1230 evaluation module in [Figure](#page-16-0) 22.

<span id="page-16-0"></span>

**Figure 22. EVM Schematic**

## **DEFINITIONS OF SPECIFICATIONS AND TERMINOLOGY**

#### **Integral Nonlinearity (INL)**

Integral nonlinearity refers to the deviation of each individual code from <sup>a</sup> line drawn from zero through full scale. The point used as zero occurs 1/2 LSB before the first code transition. The full-scale point is defined as level 1/2 LSB beyond the last code transition. The deviation is measured from the center of each particular code to the true straight line between these two end-points.

#### **Differential Nonlinearity (DNL)**

An ideal ADC exhibits code transitions that are exactly 1 LSB apart. DNL is the deviation from this ideal value. Therefore, this measure indicates how uniform the transfer function step sizes are. The ideal step size is defined here as the step size for the device under test, i.e. (last transition level - first transition level)/(2n  $-2$ ). Using this definition for DNL separates the effects of gain and offset error. A minimum DNL better than –1 LSB ensures no missing codes.

## **Offset and Gain Error**

Offset error (in LSBs) is defined as the average offset for all inputs, and gain error is defined as the maximum error (in LSBs) caused by the angular deviation from the offset corrected straight line.

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#### **Analog Input Bandwidth**

The analog input bandwidth is defined as the maximum frequency of <sup>a</sup> 1-dBFS input sine wave that can be applied to the device for which an extra 3-dB attenuation is observed in the reconstructed output signal.

## **Output Timing**

Output timing t<sub>d(O)</sub> is measured from the 50% level of the CLK input falling edge to the 10%/90% level of the digital output. The digital output load is not higher than 10 pF.

Output hold time t<sub>h(O)</sub> is measured from the 50% level of the CLK input falling edge to the10%/90% level of the digital output. The digital output load is not less than 2 pF.

Aperture delay t<sub>d(A)</sub> is measured from the 50% level of the CLK input to the actual sampling instant.

The OE signal is asynchronous.

OE timing t<sub>d(PZ)</sub> is measured from the V<sub>IH(min)</sub> level of OE to the high-impedance state of the output data. The digital output load is not higher than 10 pF.

OE timing t<sub>d(EN)</sub> is measured from the V<sub>IL(max)</sub> level of OE to the instant when the output data reaches V<sub>OH(min)</sub> or  $V_{OL(max)}$  output levels. The digital output load is not higher than 10 pF.

#### **Signal-to-Noise Ratio <sup>+</sup> Distortion (SINAD)**

SINAD is the ratio of the rms value of the measured input signal to the rms sum of all other spectral components below the Nyquist frequency, including harmonics but excluding dc. The value for SINAD is expressed in decibels.

#### **Effective Number of Bits (ENOB)**

For <sup>a</sup> sine wave, SINAD can be expressed in terms of the number of bits. Using the following formula,

• $N = (SIMAD - 1.76)/6.02$ 

it is possible to get <sup>a</sup> measure of performance expressed as N, the effective number of bits. Thus, effective number of bits for <sup>a</sup> device for sine wave inputs at <sup>a</sup> given input frequency can be calculated directly from its measured SINAD.

#### **Total Harmonic Distortion (THD)**

THD is the ratio of the rms sum of the first six harmonic components to the rms value of the measured input signal and is expressed as <sup>a</sup> percentage or in decibels.

#### **Spurious Free Dynamic Range (SFDR)**

SFDR is the difference in dB between the rms amplitude of the input signal and the peak spurious signal.

**MENTS** 

## **PACKAGING INFORMATION**



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**(3)** MSL, Peak Temp. -- The Moisture Sensitivity Level rating according to the JEDEC industry standard classifications, and peak solder temperature.

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## **TAPE AND REEL INFORMATION**





## **QUADRANT ASSIGNMENTS FOR PIN 1 ORIENTATION IN TAPE**









## **PACKAGE MATERIALS INFORMATION**



\*All dimensions are nominal



## **MECHANICAL DATA**

MTSS001C – JANUARY 1995 – REVISED FEBRUARY 1999

# **14 PINS SHOWN**

#### **PW (R-PDSO-G\*\*) PLASTIC SMALL-OUTLINE PACKAGE**

**0,30 0,65**  $\rightarrow$   $\leftarrow$   $\rightarrow$   $\leftarrow$   $\rightarrow$   $\leftarrow$   $\frac{0,30}{0.40}$   $\oplus$  0,10  $\circ$ **0,19 14 8**  $\Box$  $A$ **0,15 NOM 4,50 6,60 4,30 6,20** ↑ **Gage Plane**  $\bigcirc$ ÷  $\begin{array}{c} \begin{array}{c} \begin{array}{c} \begin{array}{c} \end{array} \end{array} \end{array} \end{array} \end{array}$  $\Box$  $\Box$ ▯  $\Box$  $\Box$ П **0,25 1 7 0**°**–8**° **A 0,75 0,50 Seating Plane 0,15**  $\sim$  0,10 **1,20 MAX 0,05 PINS \*\* 8 14 16 20 24 28 DIM** A MAX 3,10 5,10 5,10 6,60 7,90 9,80 4,90 A MIN 2,90 4,90 7,70 9,60 6,40 **4040064/F 01/97**

NOTES: A. All linear dimensions are in millimeters.

- B. This drawing is subject to change without notice.
- C. Body dimensions do not include mold flash or protrusion not to exceed 0,15.
- D. Falls within JEDEC MO-153



DW (R-PDSO-G28)

PLASTIC SMALL-OUTLINE PACKAGE



NOTES: A. All linear dimensions are in inches (millimeters).

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C. Body dimensions do not include mold flash or protrusion not to exceed 0.006 (0,15).

D. Falls within JEDEC MS-013 variation AE.



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